

# Beyond the control: idle state detection in human intracortical Brain-Computer Interfaces

D. Lesenfants<sup>1,2,4,\*</sup>, J. Saab<sup>1,2,4</sup>, B. Jarosiewicz<sup>3,4,2</sup>, B. Franco<sup>5</sup>, M. Vilela<sup>1,2</sup>, T. Hosman<sup>1,2</sup>, J. D. Simeral<sup>4,1,5,2</sup>, J. P. Donoghue<sup>4,3,1,2</sup>, L. R. Hochberg<sup>4,1,5,6,2</sup>

<sup>1</sup>Sch. of Engin., <sup>2</sup>Inst. For Brain Sci., <sup>3</sup>Dept. of Neurosci., Brown Univ., Providence, RI; <sup>4</sup>Ctr. for Neurorestoration and Neurotechnology, Rehab. R&D Service, Dept. of VA Med. Ctr., Providence, RI; <sup>5</sup>Neurol., Massachusetts Gen. Hosp., Boston, MA; <sup>6</sup>Neurol., Harvard Med. Sch., Boston, MA

\*Laboratory for Restorative Neurotechnology, 2 Stimson Av, Providence, RI 02912, USA. E-mail: damien\_lesenfants@brown.edu

**Introduction:** Brain-computer interfaces based on intracortical recordings (iBCI) have allowed people with tetraplegia to reliably control a computer cursor on a screen and perform actions with a robotic limb [1, 2]. Long-term goals of this technology include the detection of a user's intention to control the interface, allowing automatic switching between volitional neural control of assistive technologies and idle time. Idle state detection has been examined in EEG-based BCI [3] and in intracortical BCI with monkeys [4, 5]. Here, we report the ability to distinguish motor cortical activity in task-related blocks from idle inter-task periods in an individual with tetraplegia using an iBCI.

**Methods:** The participant in this study (T9) was a 52-year-old man in the BrainGate2 trial with amyotrophic lateral sclerosis. During research sessions, neural signals were recorded from two 96-channel microelectrode arrays (Blackrock Microsystems, Salt Lake City, UT) implanted into his motor cortex. Multi-unit spike rates were extracted (20ms bins) for each channel during centered-out-and-back radial-8 task blocks and during inter-task periods from five sessions in April and May of 2015. Classification performances were computed using linear discriminant analysis with a 10 fold cross-validation. First, on dataset 1 (first 10min of the session), we determined the optimal neural history (T) using the cost function CF below, constrained to a false positive (FP) rate of less than 1%. We then applied the value T on a second dataset and evaluate the positive predictive value (PPV) and negative predictive value (NPV).

$$CF(T) = \max \frac{TP(T)}{T \times FP(T)^2 + 1}, \quad \text{with } FP(T) < 1\%$$

**Results:** Optimal neural history (T) ranged between 2.86 (session E) and 3.90 (session B) seconds (mean±std: 3.30±0.38 seconds). Across all 5 sessions incorporated into this study, linear classification could distinguish idle intertask from cursor control/task periods with a positive predictive value (PPV) and a negative predictive value (NPV) above 98.5%.

**Conclusion:** In an individual with tetraplegia, idle state could be distinguished from a user's active engagement with high accuracy. Implementing this neural switch online could allow a user to turn the system on and off based on their neural activity only, without the assistance of a caregiver or expert technician. This would also remove undesirable cursor movements on the screen during user's idle periods, providing greater independence and utility for people with severe motor disabilities using iBCI communication.

**Significance:** We demonstrated that a few seconds of multi-unit spike rates activity could be used to distinguish idle from control periods during intracortical recording in a participant with tetraplegia.

**Acknowledgements:** The authors would like to thank participant T9 and his family, Beth Travers, and David Rosler, for their contributions to this research. Support provided by Office of Research and Development, Rehabilitation R&D Service, Department of Veterans Affairs (B6453R, A6779I, P1155R, N9228C), NICHD (R01HD077220, R01DC014034), NIDCD (R01DC009899), and MGH-Deane Institute.

## References:

- [1] Hochberg LR, Bacher D, Jarosiewicz B, Masse NY, Simeral JD, Vogel J, Haddadin S, Liu J, Cash SS, van der Smagt P, Donoghue JP. Reach and grasp by people with tetraplegia using a neurally controlled robotic arm. *Nature*, 485:372–5, 2012.
- [2] Hochberg LR, Serruya MD, Friehs GM, Mukand JA, Saleh M, Caplan AH, Branner A, Chen D, Penn RD, Donoghue JP. Neuronal ensemble control of prosthetic devices by a human with tetraplegia. *Nature*, 442:164–171, 2006.
- [3] Lee MH, Fazli S, Mehnert J, and Lee SW. Subject-dependent classification for robust idle state detection using multi-modal neuroimaging and data-fusion techniques in BCI. *Pattern Recognition* 2015; 48:2725-2737, 2015.
- [4] Velliste M, Kennedy SD, Schwartz AB, Whitford AS, Sohn JW, and McMorland A. Motor cortical correlates of arm resting in the context of a reaching task and implications for prosthetic control. *Journal of Neuroscience*, 34:6011–6022, 2014.
- [5] Wood F, Prabha, Donoghue JP, Black MJ. Inferring attentional state and kinematics from motor cortical firing rates. *Proc. IEEE Engineering in Medicine and Biology Society*, 1544-1547, 2005.