CHAPTER 4 SECOND-ORDER THEORY OF EQUILIBRIUM FIGURES

Eliminating S_1 between (4-93) and (4-94) yields

$$\dot{e}\left(1+\frac{4}{7}e-\frac{4}{21}m\right) = \frac{5}{2}m\left(1+\frac{8}{21}e\right) - 2e\left(1+\frac{2}{7}e\right)$$

which on multiplication by $(1 - \frac{4}{7}e + \frac{4}{21}m)$ gives the desired boundary (or initial) condition

$$\dot{e} = \frac{5}{2}m - 2e + \frac{4}{7}e^2 - \frac{6}{7}em + \frac{10}{21}m^2 \quad . \tag{4-95}$$

This is the second-order equivalent of (2-118).

As the second boundary condition we may regard the surface flattening f = f(1)as given. Furthermore, the ellipticity e must be finite at the earth's center, for $\beta = 0$.

4.2.3 Radau's Transformation

Following sec. 2.6, we introduce Radau's parameter η by

$$\eta = \frac{\beta}{e} \frac{de}{d\beta} = \frac{\beta}{e} \dot{e} \quad . \tag{4-96}$$

Substituting

$$\dot{e} = \frac{\eta}{\beta} e, \qquad \ddot{e} = \left(\frac{1}{\beta} \frac{d\eta}{d\beta} + \frac{\eta^2 - \eta}{\beta^2}\right) e$$

$$(4-97)$$

(by (2-123)) into (4-91) and dividing by e gives the second-order Radau equation

$$\beta \frac{d\eta}{d\beta} + \eta^2 - \eta - 6 + 6\frac{\delta}{D}\left(1 + \eta\right) = \frac{4}{7}\left(1 - \frac{\delta}{D}\right)\xi \quad , \tag{4-98}$$

where (4-92) takes the simpler form

$$\xi = 7\mu(1+\eta) - 3e(1+\eta)^2 - 4e \qquad (4-99)$$

in view of (4-97). Following the derivation of sec. 2.6 formula by formula, we get (2-134):

$$\frac{d}{d\beta} \left(D\beta^5 \sqrt{1+\eta} \right) = 5D\beta^4 \psi(\eta) \quad , \tag{4-100}$$

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where now

$$\psi(\eta) = (1+\eta)^{-1/2} \left[1 + \frac{1}{2} \eta - \frac{1}{10} \eta^2 + \frac{2}{35} \left(1 - \frac{\delta}{D} \right) \xi \right] \quad , \tag{4-101}$$

which is (2-132) with a small second-order correction. If $1 + \lambda_1$ denotes an average value of $\psi(\eta)$ over the range $0 \le \beta \le 1$, then the integration of (4-100) gives

$$\int_{0}^{1} D\beta^{4} d\beta = \frac{1}{5} \frac{\sqrt{1+\eta_{s}}}{1+\lambda_{1}}$$
(4-102)

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4.2 CLAIRAUT'S AND DARWIN'S EQUATIONS

since D(1) = 1.

Moments of inertia. The sum of the three principal moments of inertia A, A, and C is, by (2-138) and (4-14)

$$2A + C = 2 \iiint (x^2 + y^2 + z^2) \rho \, dv = 2 \iiint r^4 \rho \, dr \, d\sigma \quad . \tag{4-103}$$

We perform the change of variables discussed in sec. 4.1.2 to get constant limits of integration, using (4-18):

$$2A + C = 2 \iiint r^4 \frac{\partial r}{\partial q} \rho(q) dq \, d\sigma \quad . \tag{4-104}$$

If we expand r by (4-50), we immediately see that the first-order terms are removed in view of (2-5), and there remains

$$2A + C = 8\pi \int_{0}^{1} \delta \cdot \beta^{4} d\beta + O(e^{2})$$
 (4-105)

in our usual new units. This may be written

$$C = \frac{8\pi}{3} \int_{0}^{1} \delta \cdot \beta^{4} d\beta + \frac{2}{3} (C - A) \quad . \tag{4-106}$$

The integral has form (2-141) and may be brought by integration by parts into the form (2-147), so that

$$C = \frac{2}{3}M - \frac{16\pi}{9}\int_{0}^{1}D\beta^{4}d\beta + \frac{2}{3}(C-A) \quad ; \qquad (4-107)$$

note that we are using units in which, so to speak, R = 1 and $\rho_m = 1$. In these units the semimajor axis a is given by (4-46) for q = 1 as

$$a = 1 + \frac{1}{3}e + O(e^2)$$
 . (4-108)

Thus

$$Ma^{2} = MR^{2}\left(1 + \frac{2}{3}e\right) = \frac{4\pi}{3}\rho_{m}R^{5}\left(1 + \frac{2}{3}e\right)$$

which in our units reduces to

$$Ma^{2} = \frac{4\pi}{3} \left(1 + \frac{2}{3} e \right) \quad . \tag{4-109}$$

Hence the ratio (2-152),

$$\frac{J_2}{H} = \frac{(C-A)/Ma^2}{(C-A)/C} = \frac{C}{Ma^2} = \frac{C}{MR^2} \left(1 - \frac{2}{3}e\right) = \frac{C}{M} \left(1 - \frac{2}{3}e\right)$$
(4-110)

becomes, using (4-107),

$$\frac{J_2}{H} = \frac{2}{3} \left(1 - \frac{2}{3} e \right) - \frac{4}{3} \left(1 - \frac{2}{3} e \right) \int_0^1 D\beta^4 d\beta + \frac{2}{3} J_2 + O(e^2) \quad , \tag{4-111}$$

noting that in our units,

$$M = \frac{4}{3}\pi R^3 \rho_m = \frac{4\pi}{3}$$
(4-112)

and

$$\frac{C-A}{M} = \frac{C-A}{MR^2} \doteq \frac{C-A}{Ma^2} = J_2$$

To the same order we have, by (2-151)

$$J_2 = \frac{2}{3}e - \frac{1}{3}m \tag{4-113}$$

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since $e = f + O(f^2)$. Thus (4-111) becomes

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$$\frac{J_2}{H} = \frac{2}{3} \left[1 - \frac{1}{3} m - 2 \left(1 - \frac{2}{3} e \right) \int_0^1 D\beta^4 d\beta \right] \quad , \tag{4-114}$$

from which we eliminate the integral by (4-102).

Hence

$$\frac{J_2}{H} = \frac{2}{3} \left[1 - \frac{1}{3}m - \frac{2}{5} \left(1 - \frac{2}{3}e \right) \frac{\sqrt{1 + \eta_S}}{1 + \lambda_1} \right] \quad . \tag{4-115}$$

For η_S we have by (4-95) and (4-96) with $\beta = 1$,

$$1 + \eta_S = \frac{5}{2} \frac{m}{e} - 1 + \frac{4}{7} e - \frac{6}{7} m + \frac{10}{21} \frac{m^2}{e} \quad . \tag{4-116}$$

Eqs. (4-115) and (4-116) provide the extension of (2-153) to second order (Jones, 1954).

4.2.4 Darwin's Equation

It is now not difficult to derive a differential equation for the deviation $\kappa = \kappa(\beta)$. We start from the equilibrium condition (4-70) with (4-68). This gives the identity

$$(3e^2 - 8\kappa)D - 6eS + 3P + \frac{8}{3}Q = 0$$
 . (4-117)

We eliminate S by means of (4-88):

$$S = De - \frac{1}{3}D\beta \dot{e} + O(e^2) \quad , \tag{4-118}$$

obtaining

$$(-3e^2 + 2\beta e\dot{e} - 8\kappa)D + 3P + \frac{8}{3}Q = 0$$
 . (4-119)